In the Claims

1. (Currently Amended) ~~Operating~~ An operating table ~~(10)~~ comprising:

at least three elements ~~(21, 14, 16, 30, 32, 34, 36)~~ which are ~~mobile~~ moveable in relation to each other[[,]]; ~~and~~

at least two actuators, ~~(14A, 16A, 30A, 32A, 34A, 36A, 38A)~~ each controlling ~~the~~ displacement of two elements in relation to the other; ~~the table moreover comprising~~

means ~~(50, 52)~~ for driving each actuator; ~~and~~

means ~~(14B, 16B, 30B, 32B, 34B, 36B, 38B, 50, 54)~~ for detecting a risk of collision of one of the ~~operating table's mobile~~ elements with an obstacle when executing a displacement request of a first actuator[[,]]; ~~characterized in that it comprises~~

means ~~(50)~~ for determining a corrective command order of a second actuator different from the first actuator upon detecting a risk of collision, ~~the~~ wherein execution of the corrective command order by the second actuator ~~causing the~~ causes cessation of the detected risk of collision upon subsequent execution of the displacement request of the first actuator[[,]]; and

means ~~(62)~~ to make available to ~~the~~ a user ~~this~~ the corrective command order.

2. (Currently Amended) ~~Table~~ The table according to claim 1, ~~characterized in that said~~ wherein the means making available the corrective command order comprises means ~~(62)~~ for displaying the actuator to be commanded and ~~the~~ direction of the actuator command.

3. (Currently Amended) ~~Table~~ The table according to claim 1 or 2, ~~characterized in that it comprises~~ further comprising means ~~(50, 52)~~ to stop the first actuator upon detection of a risk of collision of a mobile element of the operating table with an obstacle.

4. (Currently Amended) ~~Table~~ The table according to ~~any one of the preceding claims, characterized in that said~~ claim 1, wherein the means for detecting a risk of collision of a mobile element of the operating table with an obstacle comprise means ~~(14B, 16B, 30B, 32B, 34B, 36B, 38B)~~ for determining ~~the~~ current position values of the ~~mobile~~ elements of the table.

5. (Currently Amended) ~~Table~~ The table according to claim 4, ~~characterized in that said~~ wherein the detection means comprises means ~~(50)~~ for comparing the current position values of the elements of the table with predetermined limit values.

6. (Currently Amended) ~~Table~~ The table according to claim 5, ~~characterized in that said~~ wherein the detection means comprises means ~~(58)~~ for storing the predetermined limit values.

7. (Currently Amended) ~~Table~~ The table according to claim 5, ~~characterized in that said~~ wherein the detection means comprises means for calculating predetermined limit values as a function of the current position values of ~~the~~ other elements of the table.

8. (Currently Amended) ~~Table~~ The table according to ~~any one of the preceding claims, characterized in that it comprises~~ claim 1, further comprising means ~~(50)~~ for detecting an involuntary stopping of a mobile element in displacement.

9. (New) An operating table comprising:

at least three elements which are moveable in relation to each other;

at least two actuators, each controlling displacement of two elements in relation to the other;

a controller which drives each actuator;

a sensor to detect a risk of collision of one of the elements with an obstacle when executing a displacement request of a first actuator;

a controller which determines a corrective command order of a second actuator different from the first actuator upon detecting a risk of collision, wherein execution of the corrective command

order by the second actuator causes cessation of the detected risk of collision upon subsequent execution of the displacement request of the first actuator; and

a display to view the corrective command order.